

PI2EQX6812

6.5Gbps 2-Lane (4-channel) SAS2/SATA/XAUI ReDriver™ with Equalization & De-emphasis

Features

- Up to 6.5Gbps SAS2/SATA/XAUI ReDriver™
- Supporting 4 differential channels or 2 lane
- Independent channel configuration
- Pin strap and I²C configuration controls (3.3V Tolerant)
- Adjustable receiver equalization
- Adjustable transmitter amplitude and de-emphasis
- Adjustable input threshold level
- 50-Ohm input/output termination
- Mux/Demux and loop-back features
- OOB fully supported
- Single supply voltage, 1.2V ±5%
- Active current per channel -95mA (typical)
- Power down standby mode
 - Standby current -1mA (typical)
- Automatic slumber mode power savings
 - Slumber current per channel -10mA (typical)
- Industrial operating temperature range: -40°C to 85°C
- Packaging (Pb-free & Green):
 - 42-contact TQFN (9mm x3.5mm)

Description

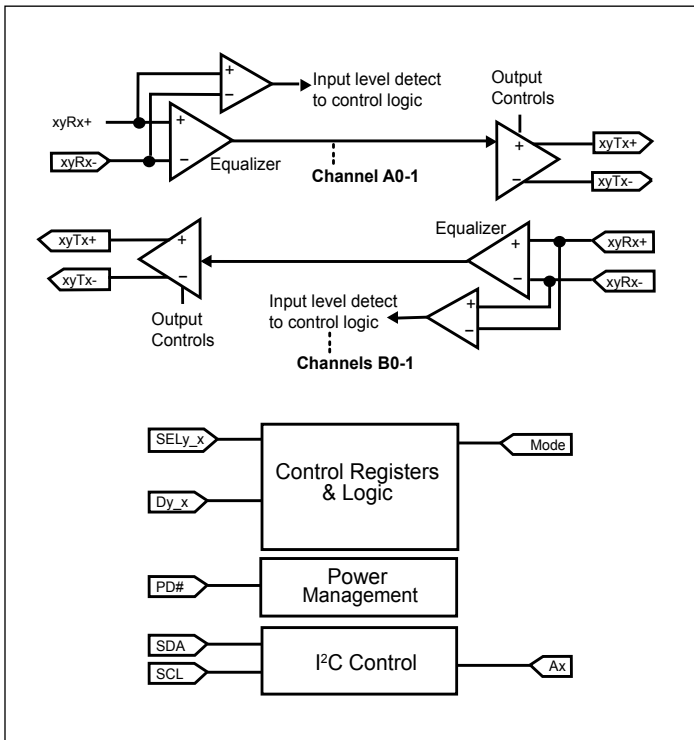
Pericom Semiconductor’s PI2EQX6812 is a low power, SAS2, 2-lane (4 differential channels) SATA, XAUI signal ReDriver™. The device provides programmable equalization, amplification, and de-emphasis by either pin strapping option or I²C Control, to optimize performance over a variety of physical mediums by reducing Inter-symbol interference.

PI2EQX6812 supports four 100-Ohm Differential CML data I/O’s between the Protocol ASIC to a switch fabric, across a backplane, or extends the signals across other distant data pathways on the user’s platform.

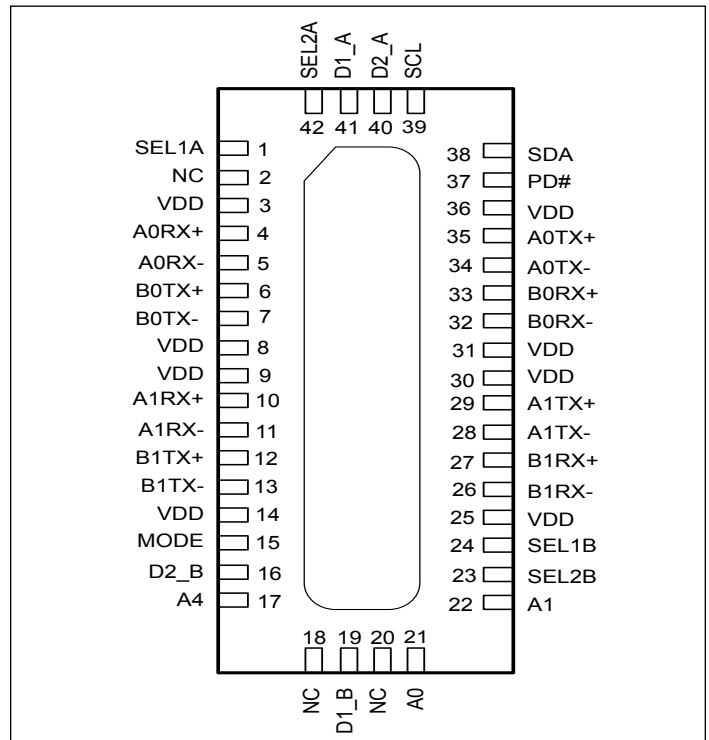
The integrated equalization circuitry provides flexibility with signal integrity of the signal before the ReDriver, whereas the integrated de-emphasis circuitry provides flexibility with signal integrity of the signal after the ReDriver.

In addition to providing signal re-conditioning, Pericom’s PI2EQX6812 also provides power management Stand-by mode operated by a Power Down pin, or through I²C register. When the input is idle, the device goes to power saving slumber mode

Block Diagram



Pin Configuration (Top-Side View)



Pin Description

Pin #	Pin Name	Type	Description
Data Signals			
4	A0RX+	I	CML inputs for Channel A0, with internal 50-Ohm pull-down. Goes to high-impedance during power-down (PD#=0).
5	A0RX-	I	
35	A0TX+	O	CML outputs for Channel A0, with internal 50-Ohm pull-up. Goes to high-impedance during power-down (PD#=0).
34	A0TX-	O	
10	A1RX+	I	CML inputs for Channel A1, with internal 50-Ohm pull-down. Goes to high-impedance during power-down (PD#=0).
11	A1RX-	I	
29	A1TX+	O	CML outputs for Channel A1, with internal 50-Ohm pull-up. Goes to high-impedance during power-down (PD#=0).
28	A1TX-	O	
33	B0RX+	I	CML inputs for Channel B0, with internal 50-Ohm pull-down. Goes to high-impedance during power-down (PD#=0).
32	B0RX-	I	
6	B0TX+	O	CML outputs for Channel B0, with internal 50-Ohm pull-up. Goes to high-impedance during power-down (PD#=0).
7	B0TX-	O	
27	B1RX+	I	CML inputs for Channel B1, with internal 50-Ohm pull-down. Goes to high-impedance during power-down (PD#=0).
26	B1RX-	I	
12	B1TX+	O	CML outputs for Channel B1, with internal 50-Ohm pull-up. Goes to high-impedance during power-down (PD#=0).
13	B1TX-	O	
Control Signals			
21, 22, 17	A0, A1, A4	I	I ² C programmable address bit A0, A1 and A4. with 100K-Ohm internal pull up
41	D[1:2]_A	I	Selection pins for Channel Ax De-emphasis (See De-emphasis Configuration Table) w/ 100K-Ohm internal pull up
40			
19	D[1:2]_B	I	Selection pins for Channel Bx De-emphasis (See De-emphasis Configuration Table) w/ 100K-Ohm internal pull up
16			
15	MODE	I	Input switch between pin control and I ² C control with internal 100k-ohm pull-up resistor. A LVCMOS high level selects input pin control, and disables I ² C operation. Note, during startup, input status of the control pin (PD#, SEL[1:2]_A/B, D[1:2]_A/B) will be latched to the initial state of some I ² C control bits only once.
2, 18, 20	NC		No Connect (Reserved for future use.)
37	PD#	I	Input with internal 100K-Ohm pull-up resistor, PD# =High or open is normal operation, PD# =Low disable the IC, and set IC to power down mode, both input and output go Hi-Z.
39	SCL	I	I ² C SCL clock input. Up to 3.3V input tolerance.
38	SDA	I/O	I ² C SDA data input/output. Up to 3.3V input tolerance
1, 42	SEL[1:2]_A	I	Selection pins for Channel Ax equalization (see Equalizer Configuration Table) w/ 100K-Ohm internal pull up

Pin #	Pin Name	Type	Description
24, 23	SEL[1:2]_B	I	Selection pins for Channel Bx Equalization (see Equalizer Configuration Table) w/ 100K-Ohm internal pull up
Power Pins			
Center Pad	GND	PWR	Supply GND
3, 8, 9, 14, 25, 30, 31, 36	V _{DD}	PWR	1.2V ± 5% Supply Voltage

Description of Operation

Configuration Modes

Device configuration can be performed in two ways depending on the state of the MODE input. MODE determines whether IC configuration is from the input pins or via I²C control. Note that the MODE pin is not latched, and is always active to enable or disable I²C access. When MODE is set high, the configuration input pins determine the configuration operating state and changes to the input configuration pins will change the operating mode.

When the MODE pin is low, programming of all control registers via I²C is allowed. During initial power-on, the value at the configuration input pins: PD#, SEL1_A, SEL2_A, D1_A, D2_A, SEL1_B, SEL2_B, D1_B, D2_B will be latched to the configuration registers as initial startup states.

Equalizer Configuration

The PI2EQX6812 input equalizer compensates for signal attenuation and Inter-Symbol Interference (ISI) resulting from long signal traces or cables, vias, signal crosstalk and other factors, by boosting the gain of high-frequency signal components. Because either too little, or too much signal compensation may be non-optimal, eight levels are provided to adjust for any application.

Equalizer configuration is performed in two ways determined by the state of the MODE pin. When the device first powers up, the SELx_[A:B] input pins are read into the appropriate control registers to set the equalization characteristic. If the MODE pin is low, reprogramming of these control registers via I²C is allowed.

In MODE = 1 (Input pin Control), each group of two channels, A and B, has separate equalization control, and all two channels within the group are assigned the same configuration state through SELx_[A:B] input pins. Through I²C register (MODE= 0), individual channel equalizer configuration can be controlled independently. The Equalizer Selection table below describes pin strapping options and associated operation of the equalizer. Refer to the section on I²C programming for information on software configuration of the equalizer.

Equalizer Selection

SEL2_[A:B]	SEL1_[A:B]	SEL0_[A:B]	@1.5GHz	@3.0GHz	Available thru Pins
0	0	0	0.8dB	1.5dB	
0	0	1	1.0dB	1.9dB	✓
0	1	0	1.5dB	3.2dB	
0	1	1	2.5dB	5.2dB	✓
1	0	0	3.5dB	6.9dB	
1	0	1	4.4dB	8.3dB	✓
1	1	0	5.9dB	10.4dB	
1	1	1	8.7dB	13.8dB	✓

Through pin selection, only SEL[1:2]_A and SEL[1:2]_B are accessible. Through I²C access, all 8 options can be selected

Output Configuration

The PI2EQX6812 provides flexible output swing and de-emphasis controls to provide the optimum signal to pre-compensate for losses across long trace or noisy environments so that the receiver gets a clean eye opening. In MODE = 1 (Input pin Control), control of output configuration is grouped for the A and B channels, so that each channel within the group has the same setting. In MODE = 0 (I²C control), each channel is independently controlled for output swing and output de-emphasis.

Output Swing Control

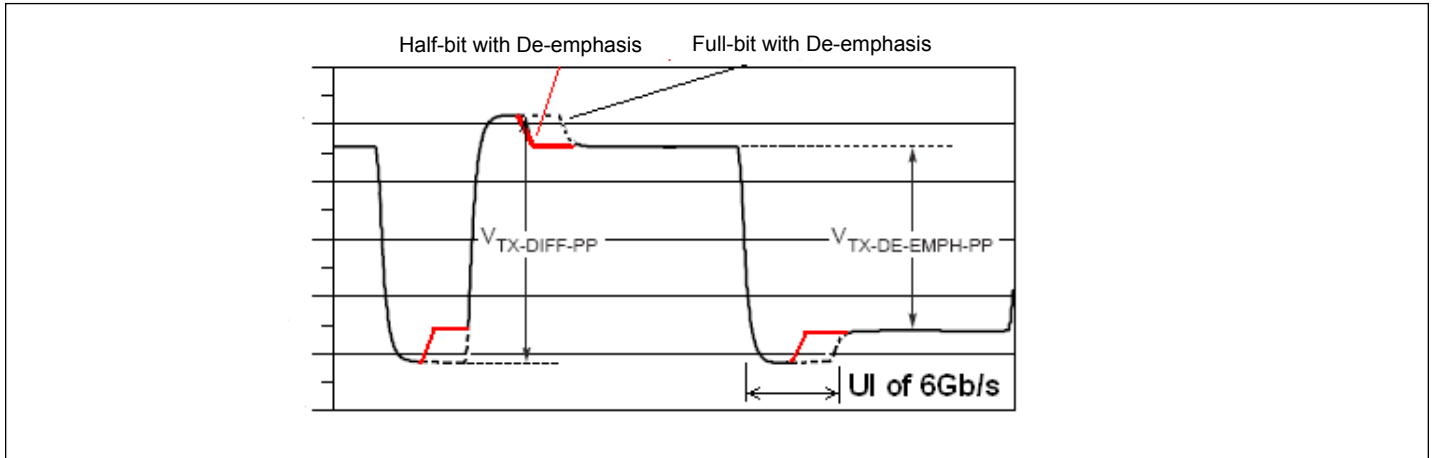
When the device first powers up, the S[1:0]_X = 00 is set. If the MODE pin is low, reprogramming of these control registers (Bit 2 and 1 of Byte 5,6,11,12) via I²C is allowed on a per channel basis.

S1_[A:B]	S0_[A:B]	Swing (Differential)
0	0	1.1V (Available for Pin Strap only)
0	1	0.5V
1	0	0.8V
1	1	1.0V

The Output Swing Control table shows available configuration settings for output level control, as specified using registers. Output swing settings are independent of the data rate.

Output De-emphasis Width Adjustment

De-emphasis settings are determined by the state of the configuration registers (Bits 4, 3 of control Registers 5, 6, 11, 12) or pins D1_A, D2_A, D1_B, D2_B, as shown in the Output De-emphasis table below. De-emphasis-half-bit is selected as the default power-on mode, but can be changed to De-emphasis-full-bit via reprogramming the Loopback and De-emphasis Control register (Bit 2 and 3 of Byte 2) using the I²C interface. Output De-emphasis settings are independent of the data rate.



Choice of half-bit or full-bit de-emphasis depends on the need for more de-emphasis (longer trace) or less de-emphasis (shorter trace) respectively.

D2_[A:B]	D1_[A:B]	De-emphasis
0	0	0dB
0	1	3.5dB
1	0	5.5dB
1	1	7.5dB

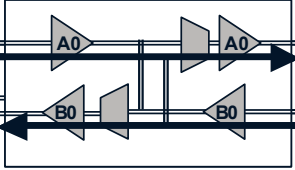
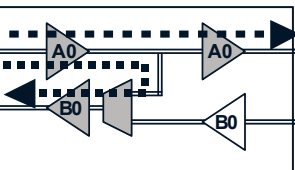
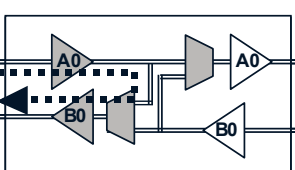
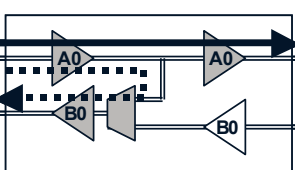
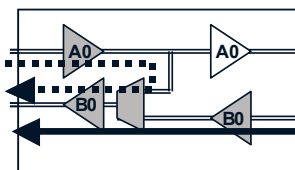
Input Level Detect

An input level detect and output squelch function is provided to all channels to eliminate re-transmission of input noise. A continuous signal level below the V_{th} threshold causes the output driver to drive both the plus and minus signal pair to the common mode voltage. The input sensitivity can be adjusted via the input level threshold register for special requirements.

Input Threshold Configuration

Bit	Threshold (mVppd)
7	180
6	160
5	140
4	120 (Default)
3	100
2	80
1	60
0	40

Loopback Operation

Loopback Modes	CONDITIONS
 <p>NORMAL MODE A0Rx to A0Tx, B0Rx to B0Tx</p>	<p>LB_A0B0# = 1 INDIS_A0 = 0 OUTDIS_A0 = 0 INDIS_B0 = 0 OUTDIS_B0 = 0</p>
 <p>BROADCAST MODE A0Rx to A0Tx and B0Tx</p>	<p>LB_A0B0# = 0 INDIS_A0 = 0 OUTDIS_A0 = 0 INDIS_B0 = 1 OUTDIS_B0 = 0</p>
 <p>LOOPBACK MODE A0Rx to B0Tx</p>	<p>LB_A0B0# = 0 INDIS_A0 = 0 OUTDIS_A0 = 1 INDIS_B0 = 1 OUTDIS_B0 = 0</p>
	<p>DEMUX MODE Solid Line A0Rx to A0Tx</p> <p>LB_A0B0# = 1 INDIS_A0 = 0 OUTDIS_A0 = 0 INDIS_B0 = 1 OUTDIS_B0 = 1</p>
	<p>DEMUX MODE Dashed Line A0Rx to B0Tx</p> <p>LB_A0B0# = 0 INDIS_A0 = 0 OUTDIS_A0 = 1 INDIS_B0 = 1 OUTDIS_B0 = 0</p>
	<p>MUX MODE Solid Line B0Rx to B0Tx</p> <p>LB_A0B0# = 1 INDIS_A0 = 1 OUTDIS_A0 = 1 INDIS_B0 = 0 OUTDIS_B0 = 0</p>
	<p>MUX MODE Dashed Line A0Rx to B0Tx</p> <p>LB_A0B0# = 0 INDIS_A0 = 0 OUTDIS_A0 = 1 INDIS_B0 = 1 OUTDIS_B0 = 0</p>

Each lane provides a loopback mode for test purposes which is controlled by a strapping pin and I²C register bit. The LB# pin controls all lanes together. When this pin is high normal data mode is enabled. When LB# is low the loopback feature is enabled. The adjacent figure diagrams this operation. Loopback is not intended to be dynamically switched, and the normal system application is to initialize to one configuration or the other.

The Loopback mode can also support mux/demux operation. Using I²C configuration, unused inputs and outputs can be disabled to minimize power and noise.

I²C Operation

The integrated I²C interface operates as a slave device, supporting standard rate operation of 100Kbps, with 7-bit addressing mode. The data byte format is 8 bit bytes, and supports the format of indexing to be compatible with other bus devices. The index, or dummy byte will have no effect on the PI2EQX6812 operation. The bytes must be accessed in sequential order from the lowest to the highest byte with the ability to stop after any complete byte has been transferred. Address bits A4, A1 and A0 are programmable to support multiple chips environment. The Data is loaded until a Stop sequence is issued.

Note that the I²C inputs, SCL and SDA operate at 1.2V logic levels, and are 3.3V tolerant.

Configuration Register Summary

Byte	Mnemonic	Function
0	SIG	Signal Detect, indicates valid input signal level
1	RSVD	Reserved for future use
2	LBDEC	Loopback and De-emphasis Control, provides for control of the loopback function and De-emphasis mode (Half-bit or Full-bit)
3	INDIS	Channel Input Disable, controls whether s channels input buffer is enabled or disabled
4	OUTDIS	Channel Output Disable, controls whether a channel output buffer is enabled or disabled.
5	A0	Channel A0 configuration
6	B0	Channel B0 configuration
11	A1	Channel A1 configuration
12	B1	Channel B1 configuration
13	VTH	Input level threshold configuration
14	RSVD	Reserved for future use

Register Description

BYTE 0 - Signal Detect (SIG)

SIG_{xy}=0=low input signal, SIG_{xy}=1=valid input signal

Bit	7	6	5	4	3	2	1	0
Name	SIG_A0	SIG_B0	Reserved	Reserved	Reserved	Reserved	SIG_A1	SIG_B1
Type	R	R	R	R	R	R	R	R
Power-on State	X	X	X	X	X	X	X	X

Note: R=Read only, W=Write only, R/W=Read and Write, X=Undefined, rsvd=reserved for future use

The Signal Detect register provides information on the instantaneous status of the channel input from the Input Level Threshold Detect circuit. If the input level falls below the V_{th}- level the relevant SIG_{xy} bit will be 0, indicating a low-level noise or electrical idle input, resulting in the outputs going to the high-impedance off state or squelch mode. If the input level is above V_{th}-, then SIG_{xy} is 1, indicating a valid input signal, and active signal recovery operation.

BYTE 1 - Reserved

Reserved Byte 1 is visible via the I²C interface. This is a read-only byte with an undefined initial state after power-up. This byte is reserved for future use.

BYTE 2 - Loopback and De-emphasis Control Register (LBDEC)

LB_{xyxy}#=0=loopback mode, LB_{xyxy}#=1=normal mode,

Slumber = 1 = auto-power down slumber enabled,

Slumber = 0 = auto power down disabled

DE_x = 0 Full-bit de-emphasis, DE_x = 1 Half-bit de-emphasis,

Bit	7	6	5	4	3	2	1	0
Name	LB_A0B0#	Reserved	Reserved	LB_A1B1#	DE_A	DE_B	Slumber	BYPASS
Type	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Power-on State	1	1	1	1	1	1	1	0

Note: R=Read only, W=Write only, R/W=Read and Write, X=Undefined, rsvd=reserved for future use

Individual control for each lane is provided for the loopback function via this register. For details on Full-bit de-emphasis and Half-bit de-emphasis, refer to Output De-Emphasis Width Adjustment Section description. Slumber mode, auto power down for all channels is enabled by slumber. Bypass is for IC manufacturing test only, and should always be set to "0" for normal operation.

BYTE 3 - Channel Input Disable (INDIS)

INDIS_{xy}=0=enable input, INDIS_{xy}=1=disable input

Bit	7	6	5	4	3	2	1	0
Name	INDIS_A0	INDIS_B0	Reserved	Reserved	Reserved	Reserved	INDIS_A1	INDIS_B1
Type	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Power-on State	0	0	0	0	0	0	0	0

Note: R=Read only, W=Write only, R/W=Read and Write, X=Undefined, rsvd=reserved for future use

The Channel Input Disable register, provides control over the input buffer of each channel independently. When and INDIS_{xy} bit is logic 1, then the input buffer is switched off and the input termination is high impedance. This feature can be used for PCB testing, and when only one input is used during Loopback as a demux function. When INDIS_{xy} is at a logic 0 state then the input buffer is enabled (normal operating mode).

BYTE 4 - Channel Output Disable (OUTDIS)

ODIS_{xy}=0=enable output, ODIS_{xy}=1=disable output

Bit	7	6	5	4	3	2	1	0
Name	ODIS_A0	ODIS_B0	Reserved	Reserved	Reserved	Reserved	ODIS_A1	ODIS_B1
Type	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Power-on State	0	0	0	0	0	0	0	0

Note: R=Read only, W=Write only, R/W=Read and Write, X=Undefined, rsvd=reserved for future use

The Channel Output Disable register, allows control over the output buffer of each channel independently. When and OUTDIS_{xy} bit is logic 1, then the output buffer is switched off and the termination is high impedance. This feature can be used for PCB testing, and when only one output is used during Loopback as a mux function. When OUTDIS_{xy} is at a logic 0 state then the output buffer is enabled (normal operating mode).

BYTE 5 - A0 Channel Configuration

BYTE 6 - B0 Channel Configuration

BYTE 11 - A1 Channel Configuration

BYTE 12 - B1 Channel Configuration

SELx_B: Equalizer configuration (see Equalizer Configuration Table)

Dx_B: De-emphasis control (see Emphasis Configuration Table)

Sx_B: Output level control (see Output Swing Configuration Table)

Bit	7	6	5	4	3	2	1	0
Name	SEL0_XX	SEL1_XX	SEL2_XX	D1_XX	D2_XX	S0_XX	S1_XX	PD#
Type	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Power-on State	1	SEL1_XX	SEL2_XX	D1_XX	D2_XX	0	0	PD#

Note: R=Read only, W=Write only, R/W=Read and Write, X=Undefined, rsvd=reserved for future use

The Ax/Bx-Channel configuration registers are used to control the input equalizer and output De-emphasis, swing levels and power-down. These register bits are loaded from the input configuration pins of the same name at power-on. These bits may be changed if the Mode input is set low to allow I²C configuration. Please refer to the tables (1) Equalizer Configuration, (2) Output Swing Configuration and (3) Output De-emphasis Configuration earlier in this document for setting information.

BYTE 7 - Reserved Default Value 00000000

BYTE 8 - Reserved Default Value 00000000

BYTE 9 - Reserved Default Value 00000000

BYTE 10 - Reserved Default Value 00000000

BYTE 13 - Input Level Threshold Configuration

Bit	7	6	5	4	3	2	1	0
Name	VTH7	VTH6	VTH5	VTH4	VTH3	VTH2	VTH1	VTH0
Type	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Power-on State	1	1	1	0	1	1	1	1

Note:

R=Read only, W=Write only, R/W=Read and Write, X=Undefined, rsvd=reserved for future use

Only 1 bit can be enabled at a time

0 = enable level, 1 = disable level,

Refer to Input Threshold Table for configuration information.

BYTE 14 Reserved

Reserved Byte 14 is visible via the I²C interface. This byte is R/W, is in an undefined state at power up, and should not be changed for normal operation. Default value 11000000

Transferring Data

Every byte put on the SDA line must be 8-bits long. Each byte has to be followed by an acknowledge bit. Data is transferred with the most significant bit (MSB) first (see the I²C Data Transfer diagram). The PI2EQX6812 will never hold the clock line SCL LOW to force the master into a wait state. a

Note: Byte-write and byte-read transfers have a fixed offset of 0x00, because of the very small number of configuration bytes. An offset byte presented by a host to the PI2EQX6812 is not used.

Addressing

Up to eight PI2EQX6812 devices can be connected to a single I²C bus. The PI2EQX6812 supports 7-bit addressing, with the LSB indicating either a read or write operation. The address for a specific device is determined by the A0, A1 and A4 input pins.

Address Assignment							
A6	A5	A4	A3	A2	A1	A0	R/W
1	1	Program	0	0	Programmable		1=R, 0=W

Acknowledge

Data transfer with acknowledge is required from the master. When the master releases the SDA line (HIGH) during the acknowledge clock pulse, the PI2EQX6812 will pull down the SDA line during the acknowledge clock pulse so that it remains stable LOW during the HIGH period of this clock pulse as indicated in the I²C Data Transfer diagram. The PI2EQX6812 will generate an acknowledge after each byte has been received.

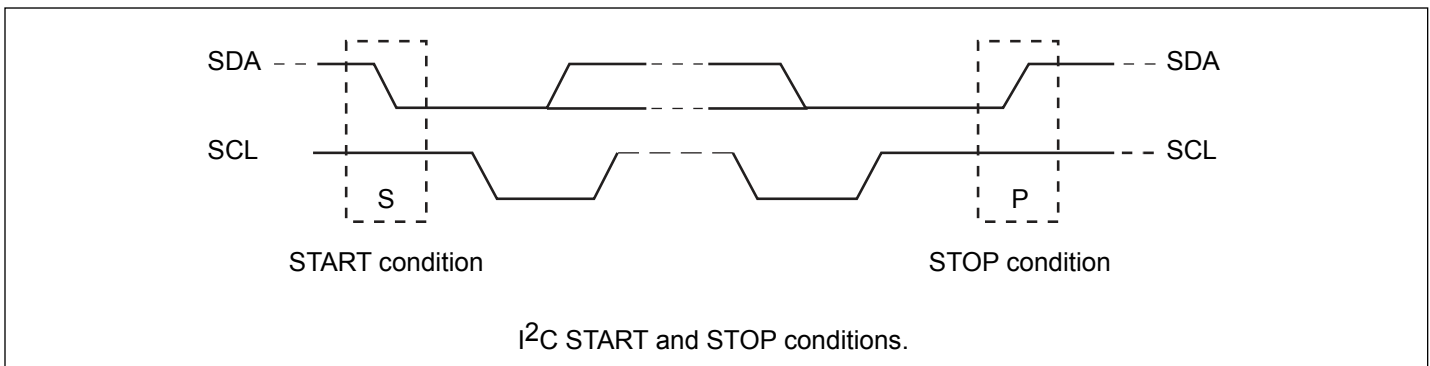
Data Transfer

A data transfer cycle begins with the master issuing a start bit. After recognizing a start bit, the PI2EQX6812 will watch the next byte of information for a match with its address setting. When a match is found it will respond with a read or write of data on the following clocks. Each byte must be followed by an acknowledge bit, except for the last byte of a read cycle which ends with a stop bit. For a write cycle, the first data byte following the address byte is a dummy or fill byte that is not used by the PI2EQX6812. This byte is provided to provided compatibility with systems implementing 10-bit addressing. Data is transferred with the most significant bit (MSB) first.

I²C Data Transfer

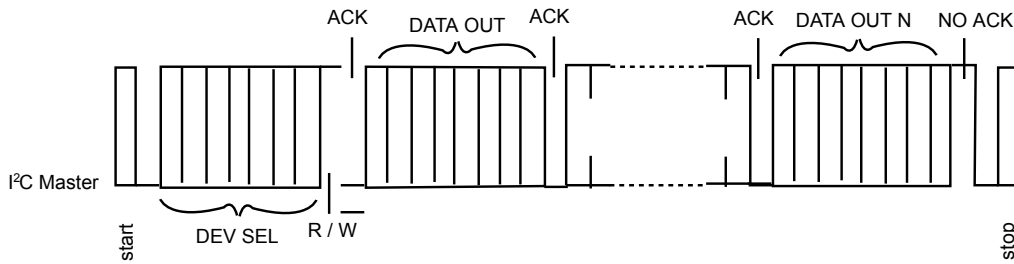
Start & Stop Conditions

A HIGH to LOW transition on the SDA line while SCL is HIGH indicates a START condition. A LOW to HIGH transition on the SDA line while SCL is HIGH defines a STOP condition, as shown in the figure below.

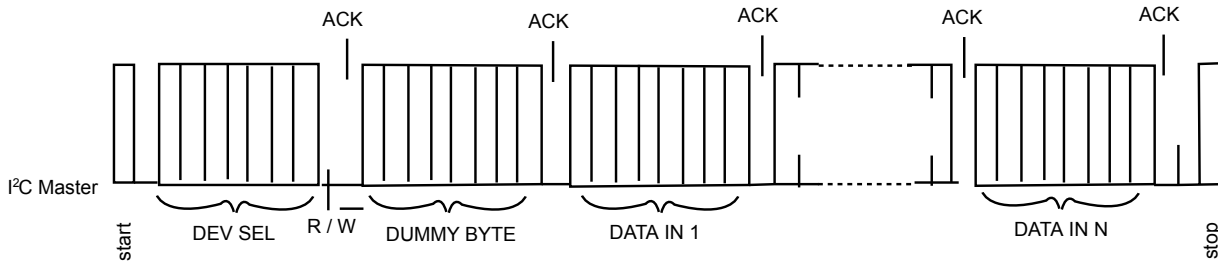


I²C Data Transfer

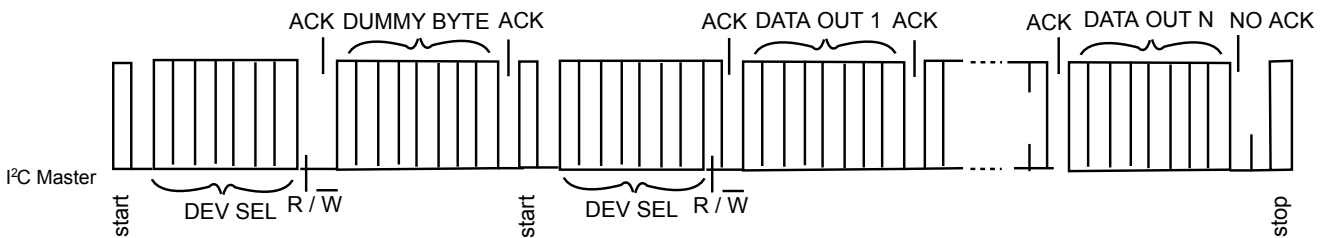
1. Read sequence



2. Write sequence



3. Combined sequence



Notes:

1. only block read and block write from the lowest byte are supported for this application.
2. for some I2C application, an offset address byte will be presented at the second byte in write command, which is called dummy byte here and will be simply ignored in this application for correct interoperation.

Maximum Ratings

(Above which useful life may be impaired. For user guidelines, not tested.)

Storage Temperature	-65°C to +150°C
Supply Voltage to Ground Potential	-0.5V to +1.45V
DC SIG Voltage	-0.5V to VDD +0.5V
Output Current	-25mA to +25mA
Power Dissipation Continuous	1W
Operating Temperature	-40°C to +85°C
ESD, HBM.....	-2kV to +2kV

Note:

Stresses greater than those listed under MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

AC/DC Electrical Characteristics

Power Supply Characteristics ($V_{DD} = 1.2V \pm 5\%$, $T_A = -40^\circ C$ to $+85^\circ C$)

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
$I_{DDactive}$	Power supply current - active	All channels switching @ 6.5 Gbps			450	mA
$I_{DDstandby}$	Power supply current - standby	PD# = 0		1	5	
$I_{DDslumber}$	Power supply current - per channel, slumber			10		
$I_{DD-channel}$	Power supply current - per channel, Active			95		

AC Performance Characteristics ($V_{DD} = 1.2V \pm 5\%$, $T_A = -40^\circ C$ to $+85^\circ C$)

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
T_{pd}	Channel latency from input to output			750		ps

CML Receiver Input ($V_{DD} = 1.2V \pm 5\%$, $T_A = -40^{\circ}C$ to $+85^{\circ}C$)

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
CML Receiver Input						
Z_{RX-DC}	DC Input Impedance		40			Ohm
$Z_{RX-DIFF-DC}$	DC Differential Input Impedance		85	100	115	
$V_{RX-DIFFP-P}$	Differential Input Peak-to-peak Voltage		240		1000	mV
$V_{RX-CM-ACP}$	AC Peak Common Mode Input Voltage				100	
V_{TH-SD}	OOB Signal detect input Threshold		75		200 ⁽¹⁾	mVppd
Equalization						
T_J	Total Jitter	Measured at 6Gbps/500			0.37	Ulp-p
D_J	Deterministic Jitter	Measured at 6Gbps/500			0.19	psrms

Note:

1. Using Compliance test at 1.5Gbps and 3Gbps. Also using OOB (OOB is formed by ALIGNp primitive or D24.3) test patterns at 1.5Gbps. The ALIGN primitive (K28.5+D10.2+D27.3 = 0011111010+0101010101+0010011100). The D24.3 = 00110011001100110011

CML Transmitter Output ($V_{DD} = 1.2V \pm 5\%$, $T_A = -40^{\circ}C$ to $+85^{\circ}C$)

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
$Z_{TX-DIFF-DC}$	DC Differential TX Impedance		80	100	120	Ohms
$V_{TX-DIFFP-P0}$	Differential Peak-to-peak Output Voltage $V_{TX-DIFFP-P} = 2 * V_{TX-D+} - V_{TX-D-} $	S[1:0] = 00, 0dB emphasis	0.9	1.1	1.3	V
		S[1:0] = 01, 0dB emphasis	0.3	0.5	0.7	
		S[1:0] = 10, 0dB emphasis	0.6	0.8	1	
		S[1:0] = 11, 0dB emphasis	0.8	1	1.2	
V_{TX-C}	Common-Mode Voltage $ V_{TX-D+} + V_{TX-D-} / 2$			$V_{DD} - 0.6$		V
t_F, t_R	Transition Time	20% to 80%			150	ps
$t_F - t_R$	Mismatch Transition Time	@3Gbps			35	%
V_{amp_bal}	TX amplitude imbalance	@3Gbps			10	
T_{skew}	TX differential skew				20	ps
V_{cm_ac}	TX AC common mode voltage	@3Gbps			50	mVpp
V_{cmOOB}	OOB common mode delta voltage				50	mV
$V_{diffOOB}$	OOB differential delta voltage				25	

PI2EQX6812

Digital I/O DC Specifications ($V_{DD} = 1.2V \pm 5\%$, $T_A = -40^{\circ}C$ to $+85^{\circ}C$)

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
V_{IH}	DC input logic high		$V_{DD}/2 + 0.2$		$V_{DD} + 0.3$	V
V_{IL}	DC input logic low		-0.3		$V_{DD}/2 - 0.2$	
V_{OH}	DC output logic high	$I_{OH} = -4mA$	$V_{DD} - 0.4$			
V_{OL}	DC output logic low	$I_{OL} = 4mA$			0.4	
V_{hys}	Hysteresis of Schmitt trigger input		0.1			
$I_{IH}^{(1)}$	Input high current				250	μA
$I_{IL1}^{(2)}$	Input low current		-250			
$I_{IL2}^{(3)}$	Input low current		-250			

Notes:

1. Includes input signals A1, A2, A4, Dx_[A:B], DE_[A:B], LB#, MODE#, PD#, Sx_[A:B], SCL, SDA, SEL_x[A:B]
2. For control inputs without pullups: SCL, SDA
3. Control inputs with pull-ups include: Dx_[A:B], DE_[A:B], LB#, MODE#, PD#, Sx_[A:B], SEL_x[A:B], A1, A2, A4

SDA and SCL I/O for I²C-bus ($V_{DD} = 1.2V \pm 5\%$, $T_A = -40^{\circ}C$ to $+85^{\circ}C$)

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
V_{IH}	DC input logic high		$0.85 \times V_{DD}$		3.6	V
V_{IL}	DC input logic low		-0.3		0.4	
V_{OL}	DC output logic low	$I_{OL} = 3mA$			0.4	
V_{hys}	Hysteresis of Schmitt trigger input		0.2			

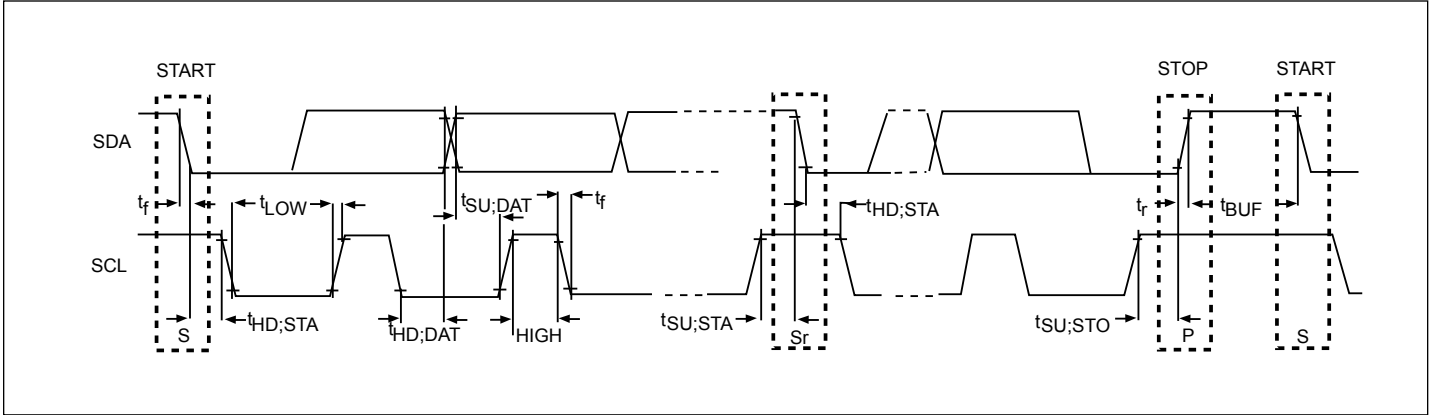
Characteristics of the SDA and SCL bus lines for Standard Mode I²C-bus devices⁽¹⁾

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
f _{SCL}	SCL clock frequency		0		–	kHz
t _{HD;STA}	Hold time (repeated) START condition. After this period, the first clock pulse is generated.		4.0		–	μs
t _{LOW}	LOW period of the SCL clock		4.7		–	
t _{HIGH}	HIGH period of the SCL clock		4.0		–	
t _{SU;STA}	Set-up time for a repeated START condition		4.7		–	
t _{HD;DAT}	Data hold time		10		–	
t _{SU;DAT}	Data set-up time		250		–	ns
t _r	Rise time of both SDA and SCL signals		-		1000	
t _f	Fall time of both SDA and SCL signals				300	
t _{SU;STO}	Set-up time for STOP condition		4.0		–	μs
t _{BUF}	Bus free time between a STOP and STOP condition		4.7		–	
C _b	Capacitive load for each bus line		-		400	pF

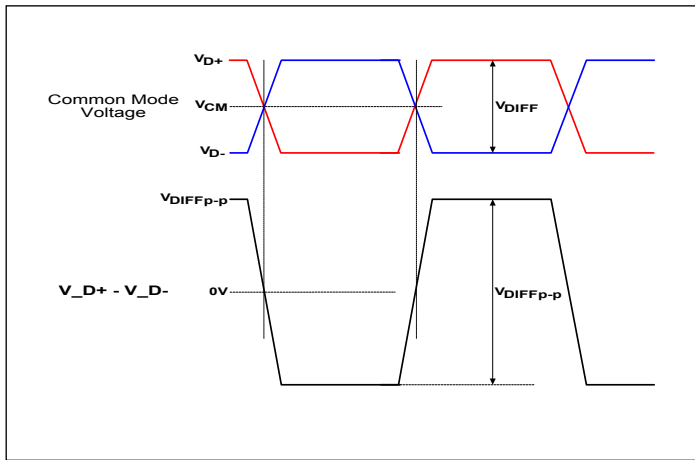
Notes:

1. All values referred to VIH min and VIL max levels

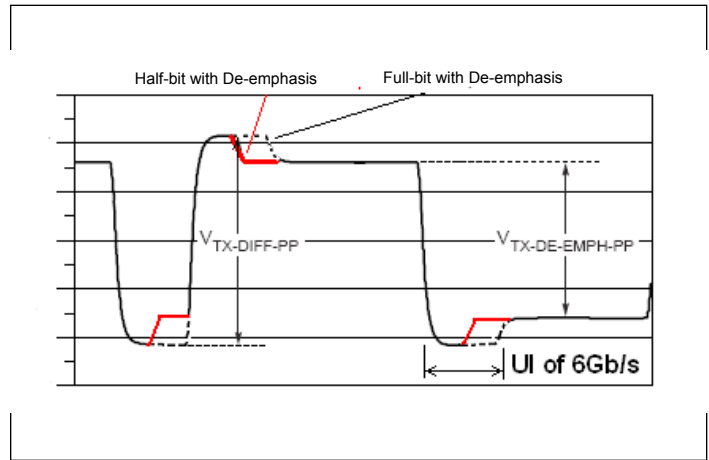
PI2EQX6812



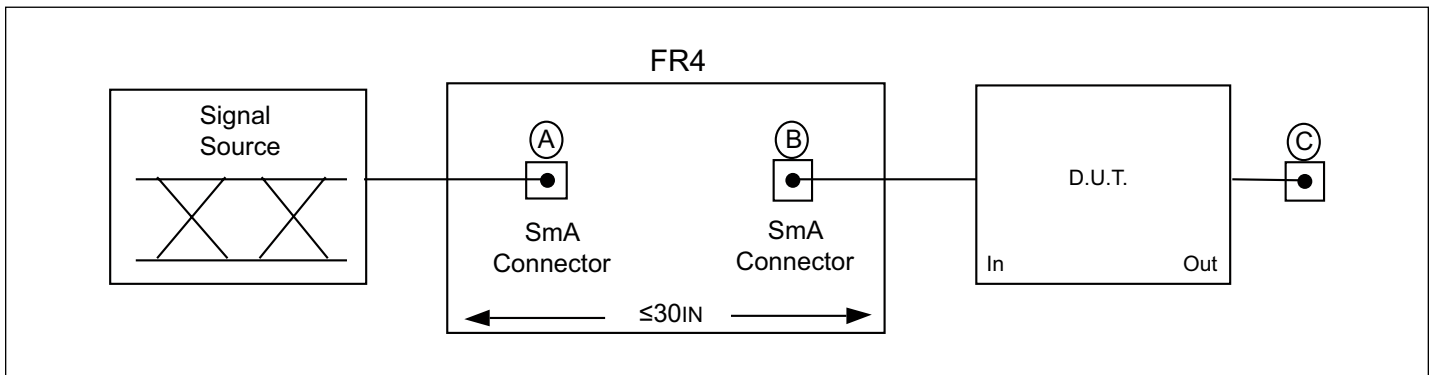
I²C Timing



Definition of Differential Voltage and Differential Voltage Peak-to-Peak



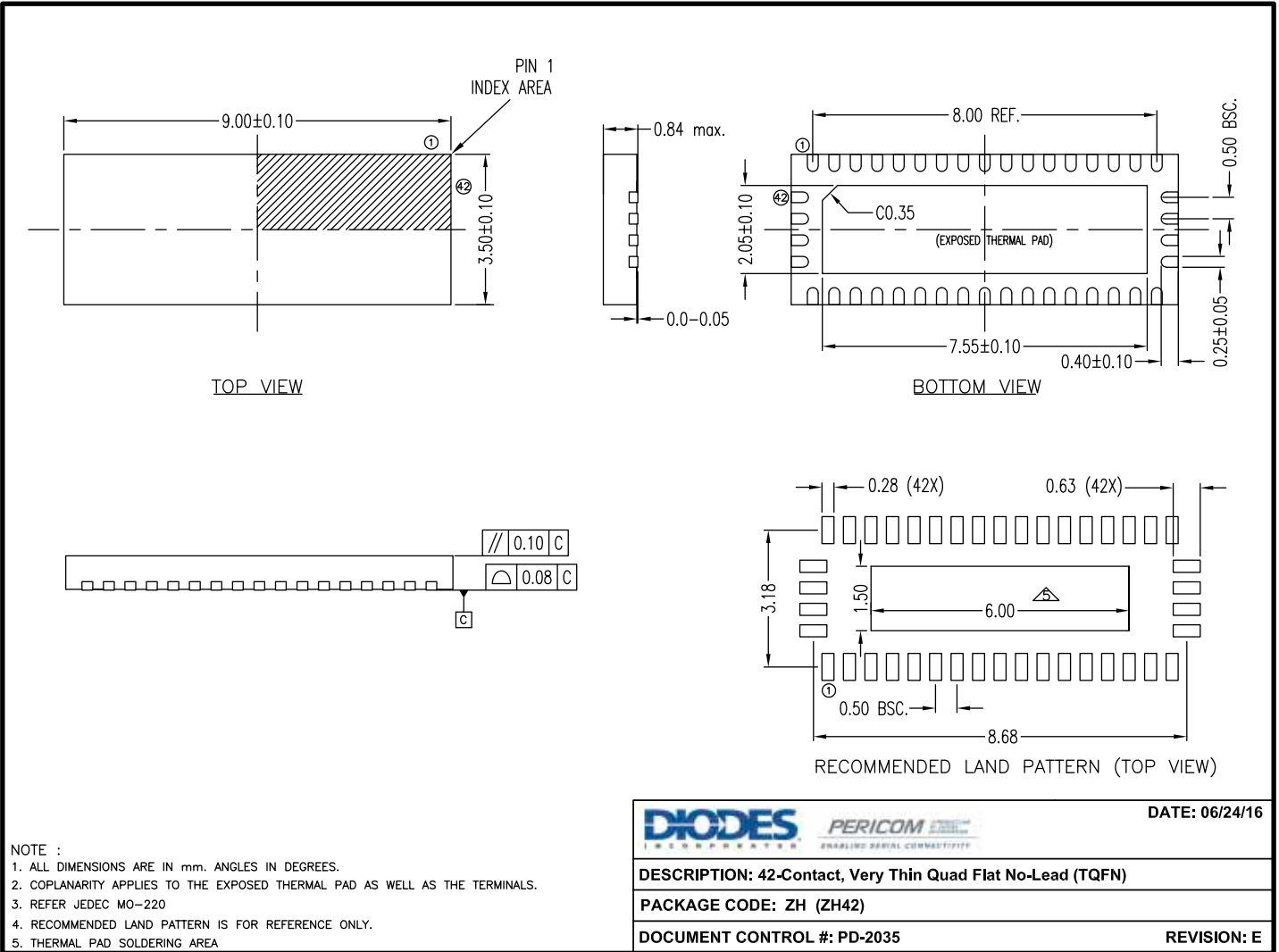
Definition of De-emphasis



AC Test Circuit Referenced in the Electrical Characteristic Table

PI2EQX6812

Packaging Mechanical: 42-Contact TQFN (ZH)



16-0136

Note: For latest package info, please check: <http://www.pericom.com/products/packaging/mechanicals.php>

Ordering Information

Ordering Number	Package Code	Package Description
PI2EQX6812ZHE	ZH	42-contact, Thin Fine Pitch Quad Flat No-Lead (TQFN)
PI2EQX6812ZHEX	ZH	42-contact, Thin Fine Pitch Quad Flat No-Lead (TQFN), Tape & Reel

Notes:

- Thermal characteristics can be found on the company web site at www.pericom.com/packaging/
- E = Pb-free and Green
- X suffix = Tape/Reel